

**Amendments to the Specification:**

Please amend the specification as follows:

Please replace paragraph number 0028 with the following rewritten paragraph:

- [0028] Next, in coaxial multiplex position detector 1, a method of determining positions of actual inner rotor 3 and outer rotor 4 will be described below. It is noted that the position measurement at detection windings of first through fourth detecting windings 7-1-1 ~~7-2-1~~ through 7-1-4 of the first couple and the position measurement at detection windings at first through fourth ~~fifth~~ detection windings 7-2-1 through 7-2-4 of the second couple are mutually the same measurement methods.

Please replace paragraph number 0029 with the following rewritten paragraph:

- [0029] Hence, the first couple of detection windings at first through fourth ~~fifth~~ detection windings 7-2-1 through 7-2-4 of the second couple are mutually the same measurement methods.

Please replace paragraph number 0032 with the following rewritten paragraph:

- [0030] Fig. 6 is an example of the coaxial multiplex position detector which is incorporated into the coaxial rotating machine. In the example of Fig. 6, coaxial rotating machine 11 includes: a stator 12, an inner rotor 13 disposed along an inner periphery of stator 12, ~~and an outer rotor 14 disposed on an outer periphery of stator 12,~~ and an outer rotor 14 disposed on an outer periphery of stator 12. In order to detect the positions of inner rotor 13 and outer rotor 14 of rotating machine 11, coaxial multiplex position detector 1 is utilized so that outer rotor 4 of coaxial multiplex position detector 1 is connected to inner rotor 13 of rotating machine 11 and inner rotor 3 of coaxial multiplex position detector 1 is connected to outer rotor 14 of rotating machine 11. It is noted that, in this embodiment, an outer rotor shaft 15 is penetrated through an inside of inner rotor 13 of rotating machine 11 is constructed as described above, the rotor connection and arrangement are not limited to this.

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (Original) A coaxial multiplex position detecting apparatus for a rotating machine, comprising:

a stator including stator pieces, each stator piece individually being split in a circumferential direction of the stator, an exciting current winding, and a detection winding, the exciting current winding and the detection winding being wound on the respective stator pieces; and

a plurality of rotors disposed on outside and inside positions of the stator in a radial direction of the stator, the respective rotors having convex and recess portions in accordance with the number of poles that the respective rotors have and having different numbers of poles according to the inside and outside positions of the rotors from each other, revolution positions of the respective rotors being determined according to an output signal of the detection winding of the stator.

2. (Currently amended) A coaxial multiplex position detecting apparatus for a rotating machine as claimed in claim 1, wherein the detection winding is constituted by four windings wound on the stator pieces in such a manner that a phase of each output signal of the four windings is different for each of 90 degrees.

3. (Currently amended) A coaxial multiplex position detecting apparatus for a rotating machine as claimed in claim 1, wherein the output signal from the detection winding detects the position of one of the rotors whose number of poles are greater than those of the other rotors by adding the output signal of the detection winding whose phase is 180° different from the output signal of the detection ~~winding~~ winding to the output signal of the same detection winding and the position of the other rotor whose number of poles is less than those of the one of the rotors is detected using the position signal of the one of the rotors whose detected number of poles is greater than those of the other of the rotors.

4. (Currently amended) A coaxial multiplex position detecting apparatus for a rotating machine as claimed in claim 2, wherein the four windings constituting the detection winding are deviated from each other by 90 degrees and a ratio of the number of poles of the respective rotors is 1:2 and the signals outputted from the four windings are as follows:

first winding of the four windings;

$$V1 = A \bullet (\cos\theta + \cos 2'\theta)$$

second winding of the four windings;

$$V2 = A \bullet (\cos(\theta - 90) + \cos 2(\theta' - 90))$$

third winding of the four windings;

$$V3 = A \bullet (\cos(\theta - 180) + \cos 2(\theta' - 180))$$

fourth winding of the four windings;

$$V4 = A \bullet (\cos(\theta - 270) + \cos 2(\theta' - 270)),$$

wherein  $\theta$  denotes a revolution position of one of the rotors whose pole number is greater than the other of the rotors,  $\theta'$  denotes a revolution position of the other of the rotors whose pole number is less than the one of the rotors, and A denotes an exciting current signal and wherein ordinarily sinusoidal wave of  $A = E \sin(\omega t)$  is added.

5. (Original) A coaxial multiplex position detecting apparatus for a rotating machine as claimed in claim 1, wherein the position ( $\theta$ ) of the one of the rotors whose number of poles is greater than the other of the rotors is detected on the basis of the following equations:  $V1 - (V1 + V3)/2$  to derive  $A \cos\theta$  and  $V2 - (V2 + V4)/2$  to derive  $A \sin\theta$  and the position ( $\theta'$ ) of the other rotor is detected on the basis of  $A \cos\theta$  and  $A \sin\theta$ , wherein A denotes a constant.

6. (Original) A coaxial multiplex position detecting apparatus for a rotating machine as claimed in claim 5, wherein the position ( $\theta$ ) of the one of the rotors whose number of poles is greater than the other of the rotors is detected by inputting  $A \cos\theta$  and  $A \sin\theta$  into a resolver-and-digital converter.

7. (Original) A coaxial multiplex detecting apparatus for a rotating machine as claimed in claim 6, wherein the resolver-and-digital converter is used to detect the respective positions ( $\theta$ ,  $\theta'$ ) of the rotors.
8. (Original) A coaxial multiplex detecting apparatus for a rotating machine as claimed in claim 6, wherein  $\text{Acos}\theta$  and  $V1$  are used to derive  $\text{Acos}2\theta'$  and  $\text{Asin}2\theta'$  and  $\text{Acos}2\theta'$  and  $\text{Asin}2\theta'$  are inputted to the resolver-and-digital converter to derive  $2\theta'$ .
9. (Original) A method applicable to a coaxial multiplex detecting apparatus for a rotating machine, comprising: providing a stator including stator pieces, each stator piece individually being split in a circumferential direction of the stator, an exciting current winding, and a detection winding, the exciting current winding and the detection winding being wound on the respective stator pieces; providing a plurality of rotors disposed on outside and inside positions of the stator in a radial direction of the stator, the respective rotors having convex and recess portions in accordance with the number of poles that the respective rotors have and having different numbers of poles according to the inside and outside positions of the rotors from each other; and determining revolution positions of the respective rotors according to an output signal of the detection winding of the stator.
10. (Original) A rotating machine in a coaxial structure comprising:  
a coaxial multiplex position detector comprising; a stator including stator pieces, each stator piece individually being split in a circumferential direction of the stator, an exciting current winding, and a detection winding, the exciting current and the detection winding being wound on the respective stator pieces; and two rotors disposed on outside and inside positions in a radial direction of the stator, the respective rotors having convex and recess portions in accordance with the number of poles that the respective rotors have and having different numbers of poles according to the inside and outside positions of the rotors from each other, the rotor positions being determined according to outputs of the detection winding of the stator, one of the outer and inner rotors of the coaxial multiplex position detector, one of the inner rotor and the outer rotor of the coaxial multiplex position detector

being attached onto an outer rotor of the rotating machine, the other rotor being attached onto an inner rotor of the rotating machine, and the stator of the coaxial multiplex position detector being fixed onto a stator of the rotating machine.